

ITION

For $n \geq 2$, the **determinant** of an $n \times n$ matrix $A = [a_{ij}]$ is the sum of n terms of the form $\pm a_{1j} \det A_{1j}$, with plus and minus signs alternating, where the entries $a_{11}, a_{12}, \dots, a_{1n}$ are from the first row of A . In symbols,

$$\begin{aligned} \det A &= a_{11} \det A_{11} - a_{12} \det A_{12} + \dots + (-1)^{1+n} a_{1n} \det A_{1n} \\ &= \sum_{j=1}^n (-1)^{1+j} a_{1j} \det A_{1j} \end{aligned}$$

$$\det \begin{bmatrix} 1 & 2 & 3 & 6 \\ 3 & 4 & 2 & 1 \\ 5 & 0 & -2 & 8 \\ 1 & 2 & 1 & 2 \end{bmatrix}$$

For each row choose a different column
example...

There are $4! = 24$ different ways to do this..

To get the determinant multiply the choices in each permutation together and add them up alternating the sign..

$\pm 2 \cdot 3 \cdot 8 + 1 + 23$ other similar terms...

Back to eigenvectors and eigenvalues...

$$Ax = \lambda x \quad \text{and try to solve for } \lambda \text{ and } x.$$

$$(A - \lambda I)x = 0$$

eliminate the x using determinants to obtain

$$\det(A - \lambda I) = 0 \quad \text{solve this for } \lambda \text{ and then find the corresponding } x\text{'s by plugging those values of } \lambda \text{ in...}$$

In general $A \in \mathbb{R}^{n \times n}$ and one of the terms in $\det(A - \lambda I)$ is the product of the diagonals

Note there are $n!$ total terms... At any rate we see $\det(A - \lambda I)$ is a polynomial of degree n .

Do we?

$$\det(A - \lambda I) = \det \left(\begin{bmatrix} 1 & 2 & 3 & 6 \\ 3 & 4 & 2 & 1 \\ 5 & 0 & -2 & 8 \\ 1 & 2 & 1 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \right)$$

$$= \det \left(\begin{bmatrix} 1-\lambda & 2 & 3 & 6 \\ 3 & 4-\lambda & 2 & 1 \\ 5 & 0 & -2-\lambda & 8 \\ 1 & 2 & 1 & 2-\lambda \end{bmatrix} \right)$$

each of these term involved
least one element that off
the diagonal...

$$= (1-\lambda)(4-\lambda)(-2-\lambda)(2-\lambda) + 23 \text{ other things}$$

poly of degree 4

largest this poly could be is degree 3...
doesn't cancel the λ^4 term
over here

$$= \text{poly of degree 4}$$

Fundamental theorem of Algebra: Every polynomial of degree n has n roots (possibly complex) counted by multiplicity.

That is, every polynomial of degree n can be factored into n factors using complex numbers.

$\det(A - \lambda I)$ in general has n roots λ counted by multiplicity.

From last week:

observation: the eigenvectors corresponding to different eigenvalues are linearly independent.

If the roots of $\det(A - \lambda I)$ are all different then the above observation means

$$Ax_1 = \lambda_1 x_1, Ax_2 = \lambda_2 x_2, \dots, Ax_n = \lambda_n x_n$$

and x_1, x_2, \dots, x_n are all linearly independent...

Since any n linearly independent vectors in \mathbb{R}^n form a basis then $\underbrace{\{x_1, x_2, \dots, x_n\}}_{\text{eigenbasis...}}$ is a basis

- If all the roots of $\det(A - \lambda I)$ are different, then it's guaranteed you have an eigenbasis.
- If some are repeated, there may or may not be an eigenbasis...

The eigenvector turns matrix-vector multiplication into scalar multiplication which is much simpler...

Why is an eigenbasis important?

$$x \in \mathbb{R}^n \text{ then } x = c_1 x_1 + c_2 x_2 + \dots + c_n x_n$$

$$Ax = c_1 \lambda_1 x_1 + c_2 \lambda_2 x_2 + \dots + c_n \lambda_n x_n$$

I've turned Ax into a sum of scalar multiplications...

Example when things go wrong

$$A = \begin{bmatrix} 3 & 1 & 0 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix}$$

$$\det(A - \lambda I) = \det \begin{pmatrix} 3-\lambda & 1 & 0 \\ 0 & 3-\lambda & 1 \\ 0 & 0 & 3-\lambda \end{pmatrix} = (3-\lambda)^3$$

eigenvalues are $\lambda = 3$ with mult. 3.

All the eigenvectors for $\lambda = 3$ are given as non-zero solutions to $Ax = 3x$.

There are the non-zero elements of $\text{Nul}(A-3I)$

$$(A-3I)x = \begin{matrix} & \text{F} & \text{P} & \text{P} \\ \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} x = 0 \end{matrix} \quad \begin{matrix} x_2 = 0 \\ x_3 = 0 \end{matrix}$$

all solutions are of the form

$$x = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_1$$

Only one linearly independent vector in $\text{Nul}(A-3I)$
so there isn't an eigenbasis in this case...