

Multiplicative Property

If A and B are $n \times n$ matrices, then $\det AB = (\det A)(\det B)$.

$A =$ product of row operations

$$A = E_1 E_2 E_3 \dots E_m E_n I$$

Then $AB = E_1 E_2 E_3 \dots E_m E_n B$

$$\det AB = \det E_1 E_2 E_3 \dots E_m E_n B$$

Theorem 3

Row Operations

Let A be a square matrix.

- If a multiple of one row of A is added to another row to produce a matrix B , then $\det B = \det A$.
- If two rows of A are interchanged to produce B , then $\det B = -\det A$.
- If one row of A is multiplied by k to produce B , then $\det B = k \cdot \det A$.

$$\det EI = \det E \det I \quad \leftarrow \text{since } \det I = 1,$$

$$\det EB = \text{by Theorem 3} = \det E \det B$$

Therefore ...

$$\det AB = \det E_1 E_2 E_3 \dots E_m E_n B$$

$$= \det E_1 \det E_2 E_3 \dots E_m E_n B$$

$$= \det E_1 \det E_2 \det E_3 \dots E_m E_n B$$

$$= (\det E_1 \det E_2 \det E_3 \cdots \det E_{n-1} \det E_n) \det B$$

$$= (\det E_1 \det E_2 \det E_3 \cdots \det E_{n-1} E_n) \det B$$

$$= (\det E_1 E_2 E_3 \cdots E_m E_n) \det B$$

$$= \det A \det B.$$

$\det A$ is a linear function of any one of its rows or columns

$$T(cx) = cT(x) \quad \text{for all scalars } c \text{ and all } x \text{ in } \mathbb{R}^n$$

$$T(u+v) = T(u) + T(v) \quad \text{for all } u, v \text{ in } \mathbb{R}^n$$

linear func. in x .

↓

$$T(x) = \det \begin{bmatrix} 1 & x_1 & 7 \\ 2 & x_2 & 8 \\ 3 & x_3 & 9 \end{bmatrix} =$$

↑ expand along this column using the definition

$$= (-1)^{1+2} x_1 \det A_{12} + x_2 \det A_{22} - x_3 \det A_{32}$$

$$= \begin{bmatrix} -\det A_{12} & \det A_{22} & -\det A_{32} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

matrix
1x3

vector
3

multiplication is
always a linear function.

$$8. \begin{vmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 2 & 7 & 6 & -3 \\ -3 & -10 & -7 & 2 \end{vmatrix} = \det \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 2 & 7 & 6 & -3 \\ -3 & -10 & -7 & 2 \end{bmatrix} \begin{array}{l} r_3 \leftarrow r_3 - 2r_1 \\ r_4 \leftarrow r_4 + 3r_1 \end{array}$$

Use Gaussian elimination

$$= \det \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 0 & 1 & 2 & 5 \\ 0 & -1 & -1 & -10 \end{bmatrix} \begin{array}{l} r_3 \leftarrow r_3 - r_2 \\ r_4 \leftarrow r_4 + r_2 \end{array}$$

$$= \det \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 0 & 0 & 0 & 10 \\ 0 & 0 & 1 & -15 \end{bmatrix} r_3 \leftrightarrow r_4$$

$$= - \det \begin{bmatrix} 1 & 3 & 2 & -4 \\ 0 & 1 & 2 & -5 \\ 0 & 0 & 1 & -15 \\ 0 & 0 & 0 & 10 \end{bmatrix} = - 1 \cdot 1 \cdot 1 \cdot 10 = -10$$

Cramer's Rule

Let A be an invertible $n \times n$ matrix. For any \mathbf{b} in \mathbb{R}^n , the unique solution \mathbf{x} of $A\mathbf{x} = \mathbf{b}$ has entries given by

$$x_i = \frac{\det A_i(\mathbf{b})}{\det A}, \quad i = 1, 2, \dots, n \quad (1)$$

↙
Gaussian elimination to find each determinant.

How many determinants? $n+1$.

- From a practical point of view solving $Ax=b$ using Gaussian elimination just once is better...

- Theoretically it's useful to have an equation for x ...

$$I = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$I_1(x) = \begin{bmatrix} x_1 & 0 & 0 & 0 \\ x_2 & 1 & 0 & 0 \\ x_3 & 0 & 1 & 0 \\ x_4 & 0 & 0 & 1 \end{bmatrix}$$

$$I_2(x) = \begin{bmatrix} 1 & x_1 & 0 & 0 \\ 0 & x_2 & 0 & 0 \\ 0 & x_3 & 1 & 0 \\ 0 & x_4 & 0 & 1 \end{bmatrix}$$

column swap

$C_1 \leftrightarrow C_2$

$$\det I_1(x) = x_1$$

$$\det I_2(x) = \sim \det$$

$$\begin{bmatrix} x_1 & 1 & 0 & 0 \\ x_2 & 0 & 0 & 0 \\ x_3 & 0 & 1 & 0 \\ x_4 & 0 & 0 & 1 \end{bmatrix}$$

$r_1 \leftrightarrow r_2$

$$= \det \begin{bmatrix} x_2 & 0 & 0 & 0 \\ x_1 & 1 & 0 & 0 \\ x_3 & 0 & 1 & 0 \\ x_4 & 0 & 0 & 1 \end{bmatrix} \sim x_2$$

Similarly

$$\det I_3(x) = x_3 \quad \text{and} \quad \det I_4(x) = x_4$$

PROOF Denote the columns of A by $\mathbf{a}_1, \dots, \mathbf{a}_n$ and the columns of the $n \times n$ identity matrix I by $\mathbf{e}_1, \dots, \mathbf{e}_n$. If $A\mathbf{x} = \mathbf{b}$, the definition of matrix multiplication shows that

$$\left[\begin{aligned} A \cdot I_i(\mathbf{x}) &= A [\mathbf{e}_1 \quad \dots \quad \mathbf{x} \quad \dots \quad \mathbf{e}_n] = [A\mathbf{e}_1 \quad \dots \quad A\mathbf{x} \quad \dots \quad A\mathbf{e}_n] \\ &= [\mathbf{a}_1 \quad \dots \quad \mathbf{b} \quad \dots \quad \mathbf{a}_n] = A_i(\mathbf{b}) \end{aligned} \right]$$

By the multiplicative property of determinants,

$$(\det A)(\det I_i(\mathbf{x})) = \det A_i(\mathbf{b})$$

divide through by $\det(A)$

The second determinant on the left is simply x_i . (Make a cofactor expansion along the i th row.) Hence $(\det A) \cdot x_i = \det A_i(\mathbf{b})$. This proves (1) because A is invertible and $\det A \neq 0$. ■

$$x_i = \det I_i(x) = \frac{\det A_i(b)}{\det A}$$

$$A [\mathbf{e}_1 \mid \mathbf{e}_2 \mid \dots \mid \mathbf{x} \mid \dots \mid \mathbf{e}_n] = [A\mathbf{e}_1 \mid A\mathbf{e}_2 \mid \dots \mid \underbrace{A\mathbf{x}}_{\mathbf{b}} \mid \dots \mid A\mathbf{e}_n]$$

$$A I_i(x) = A_i(b)$$

↑
identity with
the i th column
replaced by x

↑
 A with the
 i th column
replaced by b .

$$\det A \det I_i(x) = \det A I_i(x) = \det A_i(b)$$

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$$x_i = \frac{\det A_i(\mathbf{b})}{\det A}, \quad i = 1, 2, \dots, n \quad (1)$$

Once you have a way to solve $A\mathbf{x} = \mathbf{b}$, then you have a related way to find A^{-1} .

How, just solve $A\mathbf{x} = \mathbf{e}_i$ for $i=1, \dots, n$.

With gaussian elimination

$$[A | \mathbf{b}] \quad \text{then instead} \quad [A | \mathbf{e}_1 | \mathbf{e}_2 | \dots | \mathbf{e}_n] = [A | I]$$

with Cramer's Rule solve

$$A\mathbf{x} = \mathbf{e}_j \quad \text{using} \quad x_i = \frac{\det A_i(\mathbf{e}_j)}{\det A}$$

$$\{(i, j)\text{-entry of } A^{-1}\} = x_i = \frac{\det A_i(\mathbf{e}_j)}{\det A}$$

$$A^{-1} = \frac{1}{\det A} \begin{bmatrix} C_{11} & C_{21} & \dots & C_{n1} \\ C_{12} & C_{22} & \dots & C_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ C_{1n} & C_{2n} & \dots & C_{nn} \end{bmatrix}$$

appear reversed from how the entries in a matrix are usually indexed...