

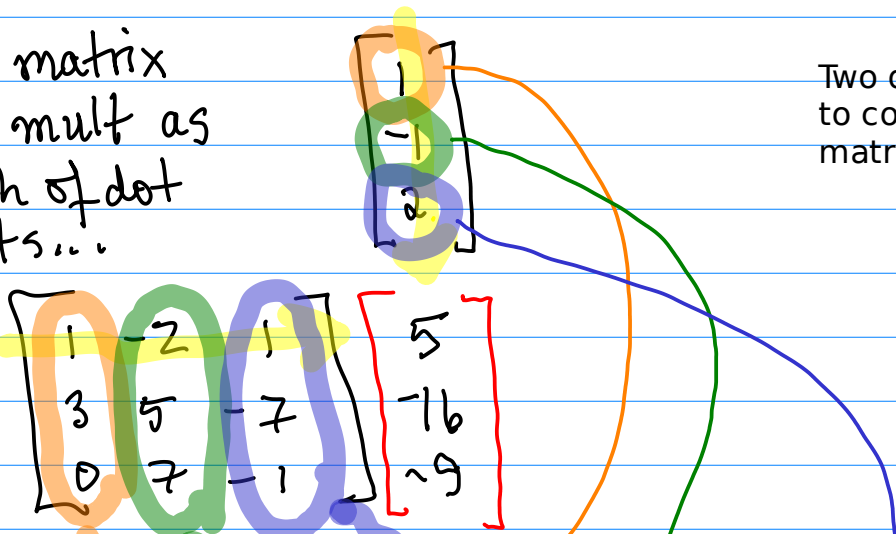
# Correspondance between matrices & linear functions:

$$A = \begin{bmatrix} 1 & -2 & 1 \\ 3 & 5 & -7 \\ 0 & 7 & -1 \end{bmatrix} \iff f(x_1, x_2, x_3)$$

$$A \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ -16 \\ -9 \end{bmatrix} = f(1, -1, 2)$$

1. Viewing matrix vector mult as a bunch of dot products...

Two different ways to compute the matrix-vector product



2. View as linear combinations of vectors...

$$A \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} \cdot 1 + \begin{bmatrix} -2 \\ 5 \\ 7 \end{bmatrix} \cdot (-1) + \begin{bmatrix} 1 \\ -7 \\ -1 \end{bmatrix} \cdot 2 = \begin{bmatrix} 5 \\ -16 \\ -9 \end{bmatrix}$$

# THEOREM 4

Let  $A$  be an  $m \times n$  matrix. Then the following statements are logically equivalent. That is, for a particular  $A$ , either they are all true statements or they are all false.

- a. For each  $\mathbf{b}$  in  $\mathbb{R}^m$ , the equation  $A\mathbf{x} = \mathbf{b}$  has a solution.
- b. Each  $\mathbf{b}$  in  $\mathbb{R}^m$  is a linear combination of the columns of  $A$ .
- c. The columns of  $A$  span  $\mathbb{R}^m$ . *← everything*
- d.  $A$  has a pivot position in every row. *← why is this the same?*

$$\begin{bmatrix} 1 & -2 & 1 \\ 3 & 5 & -7 \\ 0 & 7 & -1 \end{bmatrix} = \begin{bmatrix} | & | & | \\ a_1 & a_2 & a_3 \\ | & | & | \end{bmatrix}$$

$$a_1 = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} \quad a_2 = \begin{bmatrix} -2 \\ 5 \\ 7 \end{bmatrix} \\ a_3 = \begin{bmatrix} 1 \\ -7 \\ -1 \end{bmatrix}$$

The span is just a notation for things we already know...

$$\text{Span}(a_1, a_2, a_3) = \left\{ a_1c_1 + a_2c_2 + a_3c_3 : c_1 \in \mathbb{R}, c_2 \in \mathbb{R}, c_3 \in \mathbb{R} \right\}$$

if any of these terms you know...then the other mean exactly the same thing...

$$= \left\{ Ax : x \in \mathbb{R}^3 \right\} = \text{range}(f)$$

where  $f(x) = Ax$ .

If there is a pivot in every row then there is no row that's all zeros in the echelon form of  $A$ . which means there is no compatibility condition of the form  $0=C$  *← last time* so any right hand side is okay.

THEOREM 5

Let  $u, v$  be vectors in  $\mathbb{R}^n$ , and  $c$  is a scalar, then:

means  $f(x)$  is a linear function if

$$\begin{cases} f(x+y) = f(x) + f(y) \\ f(cx) = cf(x) \end{cases}$$

$A = [a_1 \ a_2 \ a_3]$ , and  $u, v$  in  $\mathbb{R}^3$ . (The proof of 1, 2, 3, let  $u_i$  and  $v_i$  be the  $i$ th entries in  $u$  and  $v$ , compute  $A(u+v)$  as a linear combination of the  $u$  and  $v$  as weights.

$$\begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{bmatrix}$$

$$\begin{aligned} f(-x) &= f(-1 \cdot x) \\ &= -1 \cdot f(x) = -f(x) \end{aligned}$$

How to show  $f(0)=0$ ?

$$y = -x$$

$$f(x+y) = f(x+(-x)) = f(0)$$

$$f(x) + f(y) = f(x) + f(-x) = f(x) - f(x) = 0$$

what makes zero on the right side different than other right-hand sides is that the column stays zero no matter what row operations are done

Start of Section 1.5

Homogeneous equations  $Ax = 0$

Augmented matrix

$$\left[ \begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 3 & 5 & -7 & 0 \\ 0 & 7 & -1 & 0 \end{array} \right]$$

$$r_2 \leftarrow r_2 - 3r_1$$

↑ row      ↑ col

$$\left[ \begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 0 & 11 & -10 & 0 \\ 0 & 7 & -1 & 0 \end{array} \right]$$

$$r_3 \leftarrow r_3 - \frac{7}{11}r_2$$

↑ row      ↑ col

focus on the matrix  $A$  is enough...

still zeros in this column...

margin notes made in the book during class

If  $A$  is an  $m \times n$  matrix,  $u$  a

- a.  $A(u+v) = Au + Av$ ;
- b.  $A(cu) = c(Au)$ .

definition of a linear function written in term of matrices

in one dimension a linear function is a line that passes through the origin

$$\begin{aligned} f(x) &= 3x \\ f(2) + f(5) &= 3 \cdot 2 + 3 \cdot 5 \\ &= 3(2+5) = f(2+5) \\ f(4 \cdot 2) &= 3 \cdot 4 \cdot 2 = 4 \cdot 3 \cdot 2 \\ &= 4f(2) \end{aligned}$$

$$\begin{bmatrix} 1 & -2 & 1 \\ 0 & 11 & -10 \\ 0 & 0 & \frac{59}{11} \end{bmatrix} = U$$

$$\begin{aligned} -1 &\rightarrow \frac{7}{11}(-10) \\ &= -1 + \frac{70}{11} = \frac{70-11}{11} \\ &= \frac{59}{11} \end{aligned}$$

$$A = LU$$

$$\begin{bmatrix} 1 & -2 & 1 \\ 3 & 5 & -7 \\ 0 & 7 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 7/11 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 & 1 \\ 0 & 11 & -10 \\ 0 & 0 & \frac{59}{11} \end{bmatrix}$$

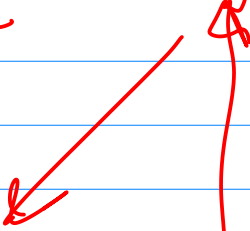
$$Ax = 0$$

$$LUx = 0$$

$$Ly = 0$$

$$Ux = y$$

System of systems



$$Ux = 0$$

To solve  $Ax = 0$   
I only need to  
solve  $Ux = 0$

$$Ly = 0$$

because of the ones always on the diagonal of L, the solution is unique

$$\begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 7/11 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{cases} y_1 = 0 \\ 3y_1 + y_2 = 0 \\ 7/11 y_2 + y_3 = 0 \end{cases}$$

$$y_2 = -3y_1 = -3 \cdot 0 = 0$$

$$y_3 = -\frac{7}{11}y_2 = -\frac{7}{11} \cdot 0 = 0$$

(note that  $y=0$  is always a solution to  $Ly=0$ )

The matrix L always has 1's on the diagonal which means the solution to  $Ly = 0$  is unique.

So  $y = 0$  is the only solution to  $Ly = 0$ .

Another way to see that the solution to  $Ax=0$  is given by  $Ux=0$  is directly from the augmented matrix...

Back to the augmented matrix for  $Ax=0$   
after elimination we get this:

$$\left[ \begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 0 & 11 & -10 & 0 \\ 0 & 0 & \frac{59}{11} & 0 \end{array} \right] \approx \left[ \begin{array}{ccc|c} U & & & 0 \\ & & & 0 \\ & & & 0 \end{array} \right]$$

Solve is the the same as solving  $Ux=0$

Some stuff highlighted from the book during the lecture...

### 1.4 THE MATRIX EQUATION $Ax = b$

If  $A$  is an  $m \times n$  matrix, with columns  $\mathbf{a}_1, \dots, \mathbf{a}_n$ , and if  $\mathbf{x}$  is in  $\mathbb{R}^n$ , then the product of  $A$  and  $\mathbf{x}$ , denoted by  $A\mathbf{x}$ , is the **linear combination of the columns** of  $A$  using the corresponding entries in  $\mathbf{x}$  as weights; that is,

$$A\mathbf{x} = [\mathbf{a}_1 \ \mathbf{a}_2 \ \dots \ \mathbf{a}_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n$$

#### EXAMPLE 3

$$\begin{bmatrix} 3 & 4 & b_1 \\ 2 & -6 & b_2 \\ 2 & -7 & b_3 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 4 & b_1 \\ 0 & 14 & 10 & b_2 + 4b_1 \\ 0 & 7 & 5 & b_3 + 3b_1 \end{bmatrix}$$

triangular arrangement

$$\sim \begin{bmatrix} 1 & 3 & 4 & b_1 \\ 0 & 14 & 10 & b_2 + 4b_1 \\ 0 & 0 & 0 & b_3 + 3b_1 - \frac{1}{2}(b_2 + 4b_1) \end{bmatrix}$$

in column 4 equals  $b_1 - \frac{1}{2}b_2 + b_3$ . The equation  $A\mathbf{x} = \mathbf{b}$  is *not* consistent cause some choices of  $\mathbf{b}$  can make  $b_1 - \frac{1}{2}b_2 + b_3$  nonzero. ■

actually how we defined  $Ax$  in the lecture and obtained linear combinations as a consequence...

#### Row-Vector Rule for Computing $Ax$

If the product  $A\mathbf{x}$  is defined, then the  $i$ th entry in  $A\mathbf{x}$  is the sum of the products of corresponding entries from row  $i$  of  $A$  and from the vector  $\mathbf{x}$ .