

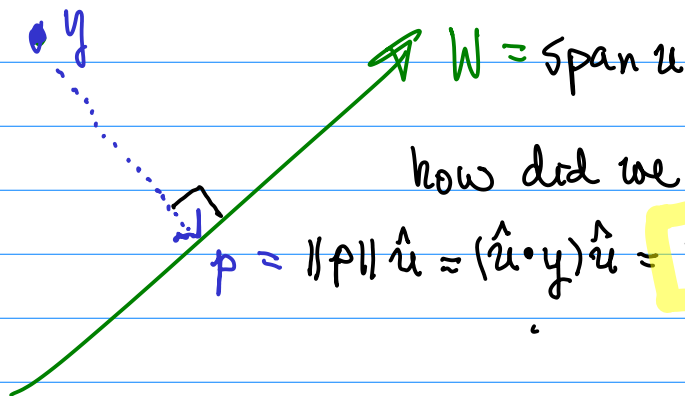
where $A = QR$ ← upper triangular, square and invertible...
 ↗ matrix with orthonormal columns

Since p is obtained by an orthogonal projection, then

$p - y$ is perpendicular to any point $w \in W$.

In one dimension

Q is playing the role of \hat{u} in higher dimensions



how did we find p in 1-d...

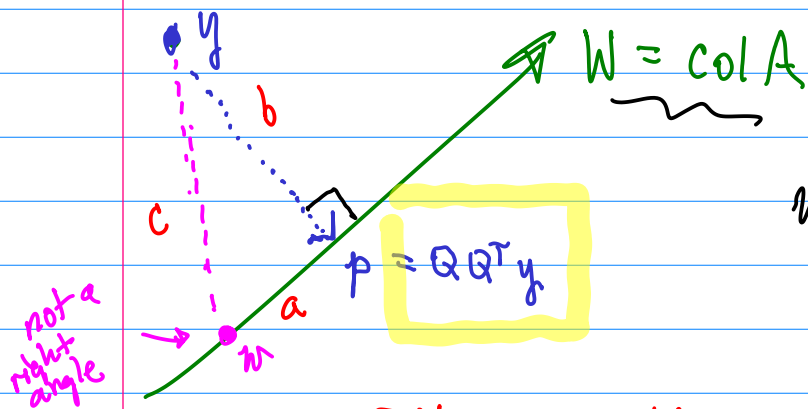
$$p = \|p\| \hat{u} = (\hat{u} \cdot y) \hat{u} = \hat{u} (\hat{u}^T y)$$

$$\|p\| = \hat{u} \cdot y = \frac{u}{\|u\|} \cdot y = \frac{(4, 5) \cdot (3, 2)}{\|(4, 5)\|} = \frac{4 \cdot 3 + 5 \cdot 2}{\sqrt{41}} = \frac{22}{\sqrt{41}}$$

Then what is p itself?

$$p = \|p\| \hat{u} = \frac{22}{\sqrt{41}} \frac{(4, 5)}{\sqrt{41}} = \frac{22}{41} (4, 5)$$

• The reason orthogonal project is useful is because p is the closest point in W to y



Why does the orthogonality condition give the minimum?

Pythagorean theorem: $a^2 + b^2 = c^2$

$$\|w - p\|^2 + \|p - y\|^2 = \|w - y\|^2$$

$$\|p - y\|^2 = \|w - y\|^2 - \|w - p\|^2 < \|w - y\|^2$$

So $\|p - y\| < \|w - y\|$ for all $w \in W$ such that $w \neq p$.

Therefore the closest point in W to y is given by $QQ^T y$.

Solve

$$Ax = b$$

$$A = QR$$

$$Q^T Q = I$$

$$QRx = b$$

$$Q^T QRx = Q^T b$$

$$Rx = Q^T b$$

↑ triangular and easy to invert etc

Last week

$$\begin{matrix}
 & \underbrace{A \in \mathbb{R}^{4 \times 3}} & & \underbrace{Q \in \mathbb{R}^{4 \times 3}} & & \underbrace{R \in \mathbb{R}^{3 \times 3}} \\
 \begin{bmatrix} 3 & -5 & 1 \\ 1 & 1 & 1 \\ -1 & 5 & -2 \\ 3 & -7 & 8 \end{bmatrix} & = & \begin{bmatrix} \frac{3}{2\sqrt{5}} & \frac{1}{2\sqrt{5}} & \frac{-3}{2\sqrt{5}} \\ \frac{1}{2\sqrt{5}} & \frac{3}{2\sqrt{5}} & \frac{1}{2\sqrt{5}} \\ \frac{-1}{2\sqrt{5}} & \frac{3}{2\sqrt{5}} & \frac{1}{2\sqrt{5}} \\ \frac{3}{2\sqrt{5}} & \frac{-1}{2\sqrt{5}} & \frac{3}{2\sqrt{5}} \end{bmatrix} & \begin{bmatrix} 2\sqrt{5} & -4\sqrt{5} & 3\sqrt{5} \\ 0 & 2\sqrt{5} & -\sqrt{5} \\ 0 & 0 & 2\sqrt{5} \end{bmatrix}
 \end{matrix}$$

What about

$$Ax = b$$

might not have a solution but

{ 4 equations } overdetermined
{ 3 unknowns } (only 3 pivots)

unless b is special this system will be inconsistent...

What does special mean? $b \in \text{col } A$

If not, then what?

Idea: minimize the error

$$E = \|Ax - b\| \quad \text{Find } x \text{ that minimizes } E.$$

Ax for all choices of x is $\text{col } A = W$

The closest point in W to b is just $p = QQ^T b$.

Thus $Ax = QQ^T b$ satisfies this minimization...

This does have a solution since $QQ^T b \in \text{col } A$.

$$QRx = QQ^T b$$

$$Q^T QRx = Q^T QQ^T b$$

$$Rx = Q^T b$$

what we had before...

6.5 Least Squares solution to $Ax = b \dots$

Idea: rewrite $Rx = Q^T b$ in terms of $A \dots$

Claim this is in the book

How does this equation look if its rewritten in terms of $A \dots$

$$A = QR$$

$$A^T A = (QR)^T (QR) = R^T Q^T QR = R^T R$$

product of invertible matrices is invertible

Square, triangular and invertible

Therefore $A^T A$ is an invertible matrix even though A itself wasn't even square.

Theorem: If the columns of A are linearly independent then $A^T A$ is invertible.

Rewrite $Rx = Q^T b$ in terms of A

$$A = QR \text{ so } Q = AR^{-1} \text{ so } Q^T = (AR^{-1})^T = (R^{-1})^T A^T$$

Therefore

$$Rx = (R^{-1})^T A^T b$$

$$x = \underbrace{R^{-1}(R^{-1})^T}_{(R^T R)^{-1}} A^T b$$

Simplify

$$(R^{-1})(R^{-1})^T = R^{-1}(R^T)^{-1} = (R^T R)^{-1} = (A^T A)^{-1}$$

Answer

$$x = (A^T A)^{-1} A^T b$$

$$A^T A x = A^T b$$

Normal equations...
for solving $Ax=b$ by
least squares...

EXAMPLE:

least-squares solution of $Ax=b$.

$$15. A = \begin{bmatrix} 2 & 3 \\ 2 & 4 \\ 1 & 1 \end{bmatrix} = \underbrace{\begin{bmatrix} 2/3 & -1/3 \\ 2/3 & 2/3 \\ 1/3 & -2/3 \end{bmatrix}}_Q \underbrace{\begin{bmatrix} 3 & 5 \\ 0 & 1 \end{bmatrix}}_R, b = \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix}$$

$Ax=b$ by least squares using QR.

$$Rx = Q^T b$$

$$Q^T b = \begin{bmatrix} 2/3 & 2/3 & 1/3 \\ -1/3 & 2/3 & -2/3 \end{bmatrix} \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{14+6+1}{3} \\ \frac{-7+6-2}{3} \end{bmatrix} = \begin{bmatrix} 7 \\ -1 \end{bmatrix}$$

$$Rx = Q^T b$$

$$\begin{bmatrix} 3 & 5 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 7 \\ -1 \end{bmatrix}$$

$$3x_1 + 5x_2 = 7$$

$$x_2 = -1$$

$$x_1 = \frac{7 - 5(-1)}{3} = 4$$

$$\text{soln: } x = \begin{bmatrix} 4 \\ -1 \end{bmatrix}$$

Now work the same problem using the normal equations:

$$A^T A x = A^T b$$

$$A = \begin{bmatrix} 2 & 3 \\ 2 & 4 \\ 1 & 1 \end{bmatrix}$$

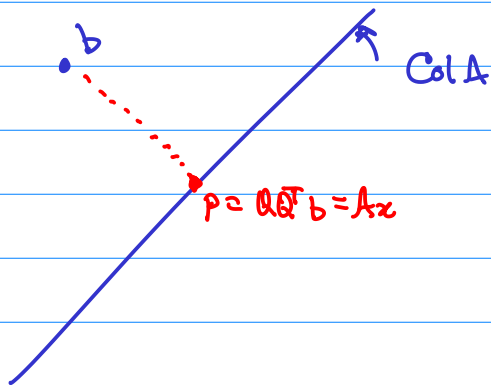
$$A^T A = \begin{bmatrix} 2 & 2 & 1 \\ 3 & 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 2 & 4 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 9 & 15 \\ 15 & 26 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} 2 & 2 & 1 \\ 3 & 4 & 1 \end{bmatrix} \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 21 \\ 34 \end{bmatrix}$$

Now solve

$$\begin{bmatrix} 9 & 15 \\ 15 & 26 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 21 \\ 34 \end{bmatrix} \quad \text{Check that } x = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \text{ is the solution.}$$

$$\begin{bmatrix} 9 & 15 \\ 15 & 26 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 36 - 15 \\ 60 - 26 \end{bmatrix} = \begin{bmatrix} 21 \\ 34 \end{bmatrix}$$



If $b \in \text{col } A$ then

$$p = b \text{ so } \boxed{QQ^T b = b}$$

could plug x back in to
 $Ax = b$

to see if it worked...
and find $\|Ax - b\|$ to
see how big it is...