

Tuesday Feb 22
Section 1005

Finish chapter 2.2

Theorem 2

Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. If $ad - bc \neq 0$, then A is invertible and

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

If $ad - bc = 0$, then A is not invertible.

This is a determinant ... Next chapter

Formula to find inverse of a 2×2 matrix

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \quad A^{-1} = \frac{1}{7-6} \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad \text{Check!}$$

so $a=1$ $b=3$
 $c=2$ $d=7$

$$A^{-1} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Identity

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Identity

find the inverse using augmented matrix

row operations

$$\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 2 & 7 & 0 & 1 \end{array} \right]$$

The Reduced-Row Echelon form is always an identity matrix?

Yes... The reduced row echelon form of an invertible matrix is always the identity matrix...

$$r_2 \leftarrow r_2 - 2r_1$$

$$\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & 1 & -2 & 1 \end{array} \right]$$

$$r_1 \leftarrow r_1 - 3r_2$$

$$\left[\begin{array}{cc|cc} 1 & 0 & 7 & -3 \\ 0 & 1 & -2 & 1 \end{array} \right]$$

$$A^{-1} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix}, \quad b = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

or

$$\begin{cases} x_1 + 3x_2 = -1 \\ 2x_1 + 7x_2 = 6 \end{cases}$$

$Ax = b$ solve using the inverse matrix...

$$A^{-1}Ax = A^{-1}b$$

$$x = A^{-1}b = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 6 \end{bmatrix} = \begin{bmatrix} -25 \\ 8 \end{bmatrix}$$

Check by plugging the answer back in

$$\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} -25 \\ 8 \end{bmatrix} = \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix}, \quad A^{-1} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix}$$

$$A^T = \begin{bmatrix} 1 & 2 \\ 3 & 7 \end{bmatrix}, \quad (A^{-1})^T = \begin{bmatrix} 7 & -2 \\ -3 & 1 \end{bmatrix}$$

↑ This is the same as $(A^T)^{-1}$

$$A^T = \begin{bmatrix} 1 & 2 & 0 \\ 3 & 7 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (A^{-1})^T = \begin{bmatrix} 7 & -2 \\ -3 & 1 \end{bmatrix}$$

Identity?

$$A = \begin{bmatrix} 1 & 3 & 0 \\ 2 & 7 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad A^{-1} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix}$$

Identity

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \quad A^{-1} = \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix}$$

Identity

The definition of the inverse

$$AA^{-1} = I$$

About transposes: $(AB)^T = B^T A^T$

$$(AA^{-1})^T = (A^{-1})^T A^T = I^T = I$$

Thus; $(A^{-1})^T A^T = I$

The definition of inverse means the inverse of A^T .

$(A^{-1})^T$ is
 $(A^T)^{-1}$ is

The Invertible Matrix Theorem

Let A be a square $n \times n$ matrix. Then the following statements are equivalent. That is, for a given A , the statements are either all true or all false.

- A is an invertible matrix.
- A is row equivalent to the $n \times n$ identity matrix.
- A has n pivot positions.
- The equation $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.
- The columns of A form a linearly independent set.
- The linear transformation $\mathbf{x} \mapsto A\mathbf{x}$ is one-to-one.
- The equation $A\mathbf{x} = \mathbf{b}$ has at least one solution for each \mathbf{b} in \mathbb{R}^n .
- The columns of A span \mathbb{R}^n .
- The linear transformation $\mathbf{x} \mapsto A\mathbf{x}$ maps \mathbb{R}^n onto \mathbb{R}^n .
- There is an $n \times n$ matrix C such that $CA = I$.
- There is an $n \times n$ matrix D such that $AD = I$.
- A^T is an invertible matrix.

difficult

maybe not so difficult

What does it mean again that the columns form a linearly independent set.

recall definition of linearly independent from chapter 17

means v_i has n elements

no free variables

$Ax = 0$ has only one solution

vectors $\{v_1, \dots, v_p\}$ in \mathbb{R}^n is said to be linearly independent

$$x_1 v_1 + x_2 v_2 + \dots + x_p v_p = 0$$

linear combination

$$A = [v_1 | v_2 | \dots | v_p]$$

same equation

$$Ax = 0$$

Moving on to chapter 24

please read

EXAMPLE 3 Let

$$A = \left[\begin{array}{ccc|cc} 2 & -3 & 1 & 0 & -4 \\ 1 & 5 & -2 & 3 & -1 \\ 0 & -4 & -2 & 7 & -1 \end{array} \right] = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}, \quad B = \begin{bmatrix} 6 & 4 \\ -2 & 1 \\ -3 & 7 \\ -1 & 3 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}$$

Chapter 2.5

LU factorization problem:

don't need to know A explicitly to solve $Ax = b$

$$6. A = \begin{bmatrix} 1 & 3 & 4 & 0 \\ 3 & -6 & -7 & 2 \\ 3 & 3 & 0 & -4 \\ -5 & -3 & 2 & 9 \end{bmatrix}, \quad b = \begin{bmatrix} 1 \\ -2 \\ -1 \\ 2 \end{bmatrix}$$

$$A = \underbrace{\begin{bmatrix} 1 & 0 & 0 & 0 \\ -3 & 1 & 0 & 0 \\ 3 & -2 & 1 & 0 \\ -5 & 4 & -1 & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} 1 & 3 & 4 & 0 \\ 0 & 3 & 5 & 2 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}}_U$$

How $LUx = b$

System $\begin{cases} Ly = b \\ Ux = y \end{cases}$

First solve $Ly = b$:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ -3 & 1 & 0 & 0 \\ 3 & -2 & 1 & 0 \\ -5 & 4 & -1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ -1 \\ 2 \end{bmatrix}$$

by substitution...

$$\begin{cases} y_1 = 1 \\ -3y_1 + y_2 = -2 \\ 3y_1 - 2y_2 + y_3 = -1 \\ -5y_1 + 4y_2 - y_3 + y_4 = 2 \end{cases}$$

$$\begin{aligned} y_2 &= -2 + 3y_1 = -2 + 3 \cdot 1 = 1 \\ y_3 &= -1 - 3y_1 + 2y_2 = -1 - 3 + 2 = -2 \\ y_4 &= 2 + 5y_1 - 4y_2 + y_3 \\ &= 2 + 5 - 4 - 2 = 1 \end{aligned}$$

Thus $y = \begin{bmatrix} 1 \\ 1 \\ -2 \\ 1 \end{bmatrix}$

Now solve $Ux = y$

$$\begin{bmatrix} 1 & 3 & 4 & 0 \\ 0 & 3 & 5 & 2 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ -2 \\ 1 \end{bmatrix}$$

by back-substitution

$$\begin{cases} x_1 + 3x_2 + 4x_3 = 1 \\ 3x_2 + 5x_3 + 2x_4 = 1 \\ -2x_3 = -2 \\ x_4 = 1 \end{cases}$$

start with the
last pivot variable

$$\begin{aligned} x_4 &= 1 \\ x_3 &= \frac{-2}{-2} = 1 \\ x_2 &= \frac{1 - 5x_3 - 2x_4}{3} \\ &= \frac{1 - 5 - 2}{3} = \frac{-6}{3} = -2 \end{aligned}$$

Answer

$$x = \begin{bmatrix} 3 \\ -2 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{aligned} x_1 &= 1 - 3x_2 - 4x_3 = 1 - 3(-2) - 4(1) \\ &= 1 + 6 - 4 = 3 \end{aligned}$$